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Two Kimberlite Model

## **Gravity Gradiometry**



$$\Gamma = \begin{bmatrix} \Gamma_{\mathrm{X}\mathrm{X}} & \Gamma_{\mathrm{X}\mathrm{Y}} & \Gamma_{\mathrm{X}\mathrm{Z}} \\ \Gamma_{\mathrm{Y}\mathrm{X}} & \Gamma_{\mathrm{Y}\mathrm{Y}} & \Gamma_{\mathrm{Y}\mathrm{Z}} \\ \Gamma_{\mathrm{Y}\mathrm{X}} & \Gamma_{\mathrm{Y}\mathrm{Y}} & \Gamma_{\mathrm{Y}\mathrm{Z}} \\ \Gamma_{\mathrm{Z}\mathrm{X}} & \Gamma_{\mathrm{Z}\mathrm{Y}} & \Gamma_{\mathrm{Z}\mathrm{Z}} \end{bmatrix} = \begin{bmatrix} \frac{\partial g_{\mathrm{X}}}{\partial \mathrm{X}} & \frac{\partial g_{\mathrm{X}}}{\partial \mathrm{Y}} & \frac{\partial g_{\mathrm{X}}}{\partial \mathrm{Z}} \\ \frac{\partial g_{\mathrm{Y}}}{\partial \mathrm{X}} & \frac{\partial g_{\mathrm{Y}}}{\partial \mathrm{Y}} & \frac{\partial g_{\mathrm{Y}}}{\partial \mathrm{Z}} \\ \frac{\partial g_{\mathrm{Z}}}{\partial \mathrm{X}} & \frac{\partial g_{\mathrm{Z}}}{\partial \mathrm{Y}} & \frac{\partial g_{\mathrm{Z}}}{\partial \mathrm{Z}} \\ \end{bmatrix}$$

where  $(g_x, g_y, g_z)$  is the Earth's gravity vector. Gravity potential satisfies Laplace's equation  $(\Gamma_{xx}+\Gamma_{yy}+$  $\Gamma_{zz}=0$  and the gradient tensor is symmetric ( $\Gamma_{ij}=\Gamma_{ji}$ 

for  $i \neq j$ ). Gravity gradient has units of Eötvos (1 Eo = 0.1 mGal/km = 10<sup>-9</sup> sec<sup>-2</sup>).

**Gradiometry vs gravimetry?** The figure above compares  $g_z$  and  $\Gamma_{zz}$  over a vertical contact. The gradient fields offer enhanced shorter wavelength information and are better at imaging shallower sources than the gravity vector components.

## **Gedex HD-AGG<sup>TM</sup> Target Performance**

Gedex Inc is developing an airborne gravity gradiometer system, the High Definition Airborne Gravity Gradiometer (HD-AGG<sup>TM</sup>), having a target noise level of 1 Eo/Hz<sup>1/2</sup> from 0.001 Hz to 1 Hz, or over wavelengths of 10s of meters to 10s of kilometers assuming aircraft speeds of 100 to 120 knots.

## The Sensor

Superconducting mechanical components, sensing coils and SQUID amplifiers are required to build a gravity gradiometer having the lowest possible intrinsic noise and the highest possible material and circuit stability. The single-axis gravity gradiometer prototype uses a pair of matched angular accelerometers and provides measurements of the gravity gradient tensor diagonal element combination  $\Gamma_{xx}$ - $\Gamma_{y}$ The full three-axis sensor (right) will also provide observations of  $\Gamma_{xx}$ - $\Gamma_{zz}$  and  $\Gamma_{yy}$ - $\Gamma_{zz}$ .

## The Platform

The Gedex HD-AGG<sup>TM</sup> design incorporates a six-degree-of-freedom motion isolation sub-system (GeoMIM) intended to reduce errors associated with the down-conversion of high-frequency platform jitter outside the signal band to lower frequencies within the signal band. The platform design incorporates both passive and active isolation.

## Quiescent Test Results

Gradiometer data were recorded at the University of Maryland (right). The square root of the power spectral density (PSD) is less than 1 Eo/Hz<sup>1/2</sup> from about 0.05 Hz to 1 Hz. With the gradiometer housed in the GeoMIM, custom temperature control electronics, and dynamics-related corrections, the target performance will be achieved in airborne mode.

DEBERS De Beers, the world leader in diamond exploration and mining, has entered into a strategic, multi-year agreement with Gedex Inc. to apply its HD-AGG<sup>TM</sup> technology in the field.









## **Kimberlite Exploration**

Kimberlites are diamond-bearing pipe-like structures composed of an upper crater, a middle diatreme, and a root. The surface area of kimberlites ranges from 0.5 to 150 Ha. The size of the kimberlite is not indicative of diamond content, i.e. whether or not it will be economic.

## Simulated AGG Surveys

Survey parameters		0.79 Ha→
Traverse Line Spacing :	100 m	ل ع ج
Control Line Spacing :	100 m	Ö 500 
Ground Clearance :	100 m	N 1000 1500
Forward Speed :	100 knots	500 X - North (m) 0 500 X - Fast (m)
Data Sampling :	2 Hz (25.5 m)	-500 -500

Two-Kimberlite Model	Thickness	Density	Radius (m)	
	(m)	(g/cc)	0.79 Ha	3.1 Ha
homogeneous overburden	50	2.0	N/A	N/A
heterogenous overburden	50	2.02-2.19	N/A	N/A
crater	200	2.25	50	100
diatreme	200	2.5	25	50
homogeneous host rock	N/A	2.6	N/A	N/A
heterogeneous host rock	N/A	2.21-2.64	N/A	N/A

### Homogenoeus Overburden and Host Rock

The 10 Eo/Hz<sup>1/2</sup> noise level (filtered) approximates the performance of operational nonsuperconducting AGG systems in fixed-wing aircraft. The spatial filter is a radial cosine taper low-pass of order 2 with roll-off start wavelength of 500 m and stop wavelength o



Combined interpretation of magnetic and gravity data are required to confirm the pres- Eo/Hz<sup>1/2</sup> ence of kimberlites in



# Benefits of a high performance airborne gravity gradiometer (HD-AGG<sup>TM</sup>) for resource exploration

## **Orebody Delineation**



The Spence deposit is a supergene-enriched copper porphyry deposit located in northern Chile. This model was part of the Mira Geoscience Ltd CAMIRO × 2000 project. The topographic relief has a maximum of 197 m and a standard deviation of 31 m. The highest point 1000 of the leach cap is less than 10 m below the surface topography. The  $\Gamma_{zz}$  response was computed on a drape surface 100 m above the ground.

Grids of random normally distributed noise having 1 and 10 Eo standard deviations were added to the  $\Gamma zz$  5000 grid. This is equivalent to 1  $Eo/Hz^{1/2}$  noise and 10  $Eo/Hz^{1/2}$  noise up to 1 Hz assuming an aircraft speed 2000of 50 m/s and a data sampling rate of 2 Hz.

The spatial filter is a radial cosine taper low-pass of order 2 with roll-off start wavelength of 700 m and stop 2000 wavelength of 300 m. The 10 Eo/Hz<sup>1/2</sup> noise level (filtered) approximates the performance of operational non-superconducting AGGs in fixed-wing aircraft.









Y - East (m)

The HD-AGG<sup>TM</sup> performance is expected to increase the number of applications in oil and gas and mineral exploration. The benefits are focused drilling programs and follow-up surveys, reduced exploration costs and value created by increased probability of discovery.



I tion of 1 Eötvos or better at spatial resolutions of 50-60 meters or better, from a fixed-wing aircraft, assuming speeds of 100 to 120 knots.

This performance level represents an order of magnitude improvement in gradient data accuracy and resolution compared to non-superconducting operational AGG systems. This provides improvement in detection and delineation of economic near-surface compact mass anomalies, and of deeper geological structure that would go undetected or be poorly resolved by operational AGG systems.

GG <sup>TM</sup> is defined by its target performance under typical survey conditions. At target
e the HD-AGG <sup>TM</sup> will provide gravity gradient data with an error standard devia-

Channel Sequence	Depth (m)	Width (m)
Shallow (141 m)	20	500
Intermediate (162)	40	1000
Deep (203 m)	60	2000

